

MANIFOLDS ADMITTING A STRUCTURE OF FOUR DIMENSIONAL ALGEBRA OF AFFINORS

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The purpose of this note is to describe some properties of manifolds endowed with an almost tangent structure T , $T^2 = 0$ and an almost complex structure J , $J^2 = -E$, $E = id$.

We consider a linear connection ∇ on N , which is compatible with the algebraic structure, i.e. $\nabla J = 0$, $\nabla T = 0$. The existence of ideals in corresponding algebra implies the existence of autoparallel submanifolds of N .

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1. ALGEBRAIC PRELIMINARIES

Let us consider a real associative algebra \mathfrak{A} with the unit element e and two generators i, ε satisfying

$$i^2 = -e, \quad \varepsilon^2 = 0,$$

under the requirement $\dim \mathfrak{A} = 4$ [1].

We distinguish three cases described by the relations

$$i\varepsilon = \varepsilon i, \tag{1.1}$$

$$i\varepsilon = -\varepsilon i, \tag{1.2}$$

$$i\varepsilon + \varepsilon i = e. \tag{1.3}$$

The corresponding algebras are denoted by $\mathfrak{A}_1, \mathfrak{A}_2, \mathfrak{A}_3$, respectively.

Proposition 1. The algebras \mathfrak{A}_1 and \mathfrak{A}_2 possess nontrivial ideals while \mathfrak{A}_3 is a simple algebra.

Proof. Let us denote $i\varepsilon = \varepsilon i = k$. Then we have the following table of multiplications of \mathfrak{A}_1

	e	i	ε	k
e	e	i	ε	k
i	i	$-e$	k	ε
ε	ε	k	0	0
k	k	$-\varepsilon$	0	0

Obviously, $\{e, i, \varepsilon, k\}$ is a basis of \mathfrak{A}_1 and $\{\varepsilon, k\}$ is an ideal with zero-multiplication.

Similarly to the previous case, \mathfrak{A}_2 admits an ideal, too.

Now we consider the algebra \mathfrak{A}_3 . The mapping

$$\varphi : \mathfrak{A}_3 \rightarrow M(2),$$

where $M(2)$ is the algebra of (2×2) real matrices defined by

$$\varphi(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \varphi(i) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad \varphi(\varepsilon) = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix},$$

is an isomorphism. It is well-known that the algebra $M(2)$ is simple. That completes the proof. □

2. MANIFOLDS OVER ALGEBRAS

Let N be a manifold of class C^∞ , TN - the tangent bundle of N , $\mathfrak{X}(N)$ - the $F(N)$ - module of global sections of TN , $F(N)$ -the ring the smooth functions on N . Let $A(TN)$ be the algebra of $F(N)$ - linear operators of $\mathfrak{X}(N)$. It can be identified with the algebra of fiber-preserving automorphisms of TN .

Let us consider a real associative algebra \mathfrak{A} with unit element e . A morphism of algebras $\Phi : \mathfrak{A} \rightarrow A(TN)$ such that $\Phi(e) = I$, the identity operator of $A(TN)$ will be called an \mathfrak{A} - *structure* on N . A linear connection ∇ on N is said to be *compatible* with the \mathfrak{A} - *structure* if $\nabla\Phi(a) = 0$, for all $a \in \mathfrak{A}$, i.e. each operator $\Phi(a)$ is parallel with respect to ∇ . An \mathfrak{A} - *structure* is said to be *integrable* if for each point p exists a neighborhood U , such that the operator $\Phi(a)$ for all $a \in \mathfrak{A}$ have constant components in corresponding coordinate chart.

If \mathfrak{B} is an ideal of \mathfrak{A} , we define a distribution D in TN as follows:

$$D_p = \{\Phi(b)v \in T_pN; \text{ for all } b \in B \text{ and } v \in T_pN\}.$$

In other words, at each point $p \in N$, D_p is the image of T_pN by the operators corresponding to the elements of \mathfrak{B} . This distribution is invariant with respect to all operators $\Phi(a)$, $a \in \mathfrak{A}$.

Proposition 2. Let \mathfrak{A} is associative unitary R -algebra, N be a manifold with \mathfrak{A} - structure and ∇ be a linear connection on N . If $\nabla\Phi(a_i) = 0$ for all basis elements a_i of \mathfrak{A} then ∇ is compatible with \mathfrak{A} . \square

Proof. The operator $\nabla : \mathfrak{D}(N) \rightarrow \mathfrak{D}(N)$ is a differentiation of the tensor algebra on N . If $\Phi(a_i) = A_i \in \mathfrak{D}_1^1(N)$, $i = 1, 2, 3, 4$, it follows that

$$\nabla_X(A_i A_j) = \nabla_X(A_i)A_j + A_i \nabla_X(A_j) = 0$$

\square

The following theorem is proved in [2], p. 118.

Theorem 1. Let (M, ∇) be an affinely connected analytical manifold equipped with an \mathfrak{A} - structure compatible with ∇ . Then the following properties are satisfied:

1. The distribution D is involutive;
2. If N' is a maximal integral submanifold of D through any point of N , then it is autoparallel submanifold of N ;
3. On each N' acts the quotient - algebra $\mathfrak{A}/O(\mathfrak{B})$, where $O(\mathfrak{B})$ is the annihilator of the ideal \mathfrak{B} in algebra \mathfrak{A} .

3. ALGEBRAIC STRUCTURES $\mathfrak{A}_1, \mathfrak{A}_2, \mathfrak{A}_3$

The integrability conditions of these structures are given in [1].

According to the previous notations, we set $\Phi(e) = I$, $\Phi(i) = J$ and $\Phi(\varepsilon) = T$, by I we denote the unit matrix and we set $JT = K$. Moreover, we suppose that

$$Im T = Ker T = \frac{1}{2} dim N.$$

Theorem 2. Let N be a manifold with an integrable algebraic structure of type \mathfrak{A}_i , ($i = 1, 2$) and ∇ be torsion-free connection compatible with the algebraic structure, i.e. $\nabla J = 0, \nabla T = 0$. Then there exists an \mathfrak{A}_i - invariant foliation N' in N , i.e. at any point $p \in N' \subset N$ the tangent space T_pN' is invariant with respect to J and T .

Proof. Case (1): $J^2 = -I, T^2 = 0, JT = TJ$ and $\text{Ker } T = \text{Im } T$. We denote by D the distribution $\text{Ker } T = \text{Im } T$. It can be easily seen that the following holds: $JD \subseteq D, TD \subseteq D$. This implies that $n \equiv 0 \pmod{4}$, so we can write $n = 4m$.

For any point of N there exist an open neighborhood with a chart (x^1, \dots, x^{4m}) on it such that with respect to the basis $\partial/\partial x^1, \dots, \partial/\partial x^{4m}$ the tensors J and T have matrix expression:

$$\begin{pmatrix} 0 & -I & 0 & 0 \\ I & 0 & 0 & 0 \\ 0 & 0 & 0 & -I \\ 0 & 0 & I & 0 \end{pmatrix} \text{ and } \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ I & 0 & 0 & 0 \\ 0 & I & 0 & 0 \end{pmatrix}, \quad K = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -I & 0 & 0 \\ I & 0 & 0 & 0 \end{pmatrix}.$$

We denote $(x^1, \dots, x^{4m}) = (x^i, x^{i+m}, x^{i+2m}, x^{i+3m})$, $(i = 1, \dots, m)$. Every integral submanifold N' of $D = \text{Im } T$ has coordinates $(x_0^i, x_0^{i+m}, x_0^{i+2m}, x_0^{i+3m})$.

We have $\mathfrak{A} = \{I, J, T, K\}$, $\mathfrak{B} = \{T, K\}$ - an ideal, the annihilator $O(\mathfrak{B}) = \mathfrak{B}$, $\mathfrak{A}/O(\mathfrak{B}) \approx \{I, J\}$.

The restriction of J on D is the following

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -I \\ 0 & 0 & I & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ v^{i+2m} \\ v^{i+3m} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -v^{i+3m} \\ v^{i+2m} \end{pmatrix}.$$

Here $v = (0, 0, v^{i+2m}, v^{i+3m}) \in D$ and by I we denote the unit $(n \times n)$ - matrix.

Case (2): $JT = -TJ$.

Let M be a manifold provided with a \mathfrak{A}_2 - structure. Similarly to the previous case, one may choose an atlas, such that with respect to any chart $U_x \subset N$ the operators J and T have the form

$$\begin{pmatrix} 0 & -I & 0 & 0 \\ I & 0 & 0 & 0 \\ 0 & 0 & 0 & -I \\ 0 & 0 & I & 0 \end{pmatrix} \text{ and } \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ I & 0 & 0 & 0 \\ 0 & -I & 0 & 0 \end{pmatrix}.$$

Theorem 2 is proved. □

Now we start considering the last case.

Case (3): N is a manifold provided with a couple J, T of tensor fields of type $(1,1)$, satisfying $J^2 = -I, T^2 = 0$ and $JT + TJ = I$. Here it is not necessary to require that $\text{Ker } T = \text{Im } T$, because it follows from the relation between J and T . Obviously, we can write $n = 2m$.

Proposition 3. An \mathfrak{A}_3 - structure on a smooth manifold N may be given equivalently:

1. By the operators P and Q , such that

$$P^2 = I, \quad Q^2 = I \quad \text{and} \quad PQ + QP = 0,$$

2. By the operators J and P , such that

$$J^2 = -I, \quad P^2 = I \quad \text{and} \quad JP = -PJ.$$

Proof: 1. If we set $P = JT - TJ$ and $Q = J + 2T$, by using the characteristic identity in *Case (3)* we have

$$\begin{aligned} P^2 &= (JT - TJ)(JT - TJ) = JTJT - JTTJ - TJJT + TJTJ \\ &= JT(I - TJ) + TJ(I - JT) = JT + TJ = I, \\ Q^2 &= (J + 2T)(J + 2T) = J^2 + 2JT + 2TJ = -I + 2I = I. \end{aligned}$$

2. In analogy with the previous case we have

$$\begin{aligned} JP &= J(JT - TJ) = J^2T - JTJ = -T - J(I - JT) \\ &= -T - J - T = -J - 2T, \\ PJ &= (JT - TJ)J = JTJ + T = J(I - JT) + T = J + 2T. \end{aligned}$$

Remark 1. In [1] the structure $\{J, P\}$ is called a *complex product structure*.

The next theorem is a modification of the result of A. Andrada [3].

Theorem 3. *Let N be a manifold with an \mathfrak{A}_3 -structure, given by the operators $\{J, T\}$. Then:*

1. *There exists a unique torsion-free connection ∇ with respect to which J and T are parallel;*
2. *The leaves of the distribution $\mathfrak{D} = \text{Im} T$ are flat autoparallel submanifolds of N .*

Proof. The connection ∇ , which preserves the tensor fields J and P is given by

$$\begin{aligned} \nabla_x Y &= \frac{1}{4} \{ [X, Y] - [PX, PY] + P[X, PY] - P[PX, Y] \\ &\quad - J[X, JY] - J[PX, Q] + Q[X, QY] + Q[PX, JY] \}, \end{aligned}$$

where $Q = -JP$.

Since $T = \frac{1}{2}(PJ - J)$, it follows that $\nabla P = \nabla J = 0$. Our assertion follows from Proposition 2.

We may choose an atlas on N , whose Jacobian matrices are local constant. Then the operators J and T have the following form

$$\begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 0 & 0 \\ I & 0 \end{pmatrix},$$

where I is the unit $(n \times n)$ -matrix. The theorem is proved. □

Remark 2. Another proof of the existence and uniqueness of ∇ is given in [1].

Remark 3. In this case the distribution $D = \text{Im}T$ is not invariant with respect to the operator J .

Remark 4. As it is shown in [1], [3] the connection ∇ does not need to be flat.

An essential property of the tangent bundle TM is the fact that it bears a *tangent structure*. More precisely, let $\pi : TM \rightarrow M$ and $K : TTM \rightarrow TM$ be natural projection and connection maps of ∇ , respectively. If X is a vector field on M , we may define vertical lift X^v and horizontal lift X^h on TM by the relations

$$\begin{aligned}(d\pi)X^v &= 0, & KX^v &= X, \\ (d\pi)X^h &= X, & KX^h &= 0.\end{aligned}$$

From a basis $\{X_1, \dots, X_n\}$ of $\mathfrak{X}(M)$ we get the basis of $\mathfrak{X}(TM) : \{X_k^h, X_n^v\}$, $k = 1, \dots, n$. With respect to this basis the tangent structure has the matrix expression mentioned above. We define

$$\tilde{J} : X^h \rightarrow X^v, \quad X^v \rightarrow -X^h, \quad \tilde{J}^2 = -I.$$

By setting $J = -\tilde{J}$, this leads us to the \mathfrak{A}_3 algebra.

Theorem 4. *The manifold TM can be endowed with integrable operators P , Q , subject to the relations*

$$P^2 = I, \quad Q^2 = I, \quad PQ = QP = 0.$$

Proof. Let us set $P = JT - TJ$ and $Q = J + 2T$. By using the identity in Case (3) of Theorem 2, we can easily verify our statement.

The integrability of J and T implies the integrability of P and Q . □

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